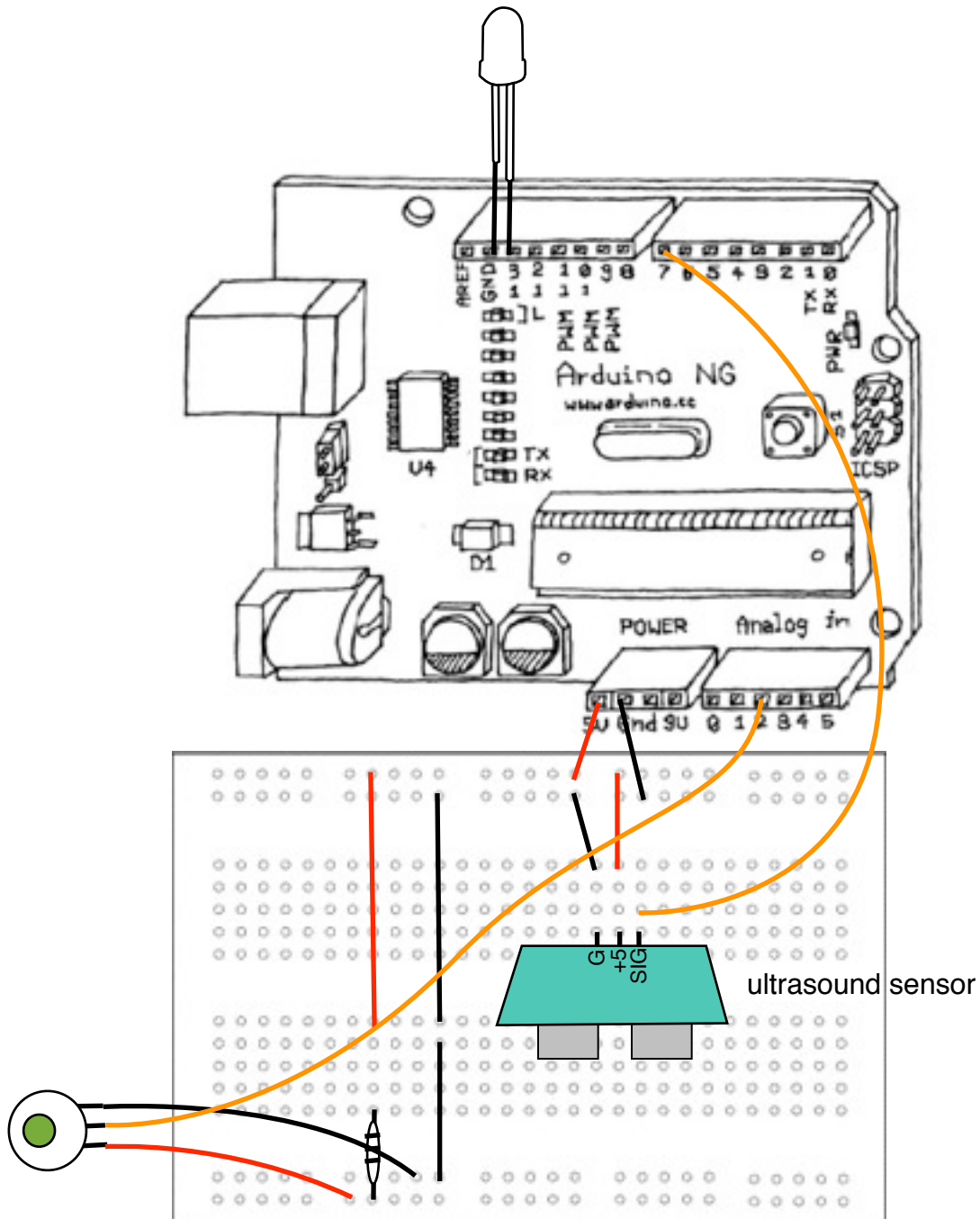


## Ultrasound sensor, led, potentiometer

Program an ultrasound sensor to send out an ultrasound wave and then listen for it to bounce back while counting time. *This is the same technique that bats use to locate their prey.* Program an LED to turn on at particular distance or range from the sensor. Instead of using your body or an object to turn your LED to turn on, use a potentiometer to locate this distance at a certain point in its rotation. The potentiometer has a range of 0 to 1023. This range can be narrow (making bigger steps) by dividing it by an integer.



```
// Send a wave out with an ultrasound sensor; Use a potentiometer to turn on an LED at a particular distance from the sensor.
```

```
int ultraSoundpin = 7;  
int ledPin = 13;  
unsigned long ultrasoundDuration;
```

```
int potPin = 2; // select the input pin for the potentiometer  
int val = 0; // variable to store the value coming from the potentiometer
```

```
void setup() {  
  beginSerial(9600);  
}
```

```
void loop() {  
  // switch pin to output  
  // sensor sends an ultrasound wave out and then waits for the wave to bounce back  
  // same tech as dolphins and bats
```

```
  pinMode(ultraSoundpin, OUTPUT); // usually set in void loop  
  pinMode(ledPin, OUTPUT);
```

```
  // send a low, wait 2 microseconds, send a high then wait 10 microseconds  
  // switches ultrasound sensor pin from output to input; sensor waits to receive ultrasound  
  // wave; counts how long the ultrasound wave has been gone (time) before bouncing back
```

```
  digitalWrite(ultraSoundpin, LOW);  
  delayMicroseconds(2);  
  digitalWrite(ultraSoundpin, HIGH);  
  delayMicroseconds(10); // length of wave  
  digitalWrite(ultraSoundpin, LOW);
```

```
  // switch pin to input  
  pinMode(ultraSoundpin, INPUT);
```

```
  // wait for a pulse to come in as high  
  ultrasoundDuration = pulseIn(ultraSoundpin, HIGH);
```

```
  // output  
  Serial.print(ultrasoundDuration); //  
  //Serial.print("\t");  
  Serial.print(ultrasoundDuration/58, DEC);  
  //Serial.print(" cm");  
  Serial.println();  
  val = analogRead(potPin); // read the value from the sensor, fine-tune sensor  
  //val = val / 3; // to get a narrower range with bigger steps in between "uncomment" this line  
  // of code to divide your analog value by 3 or any number
```

```
if(ultrasoundDuration < val){  
  digitalWrite(ledPin, HIGH);  
}  
else  
{  
  digitalWrite(ledPin, LOW);  
}  
delay(100);  
}
```